

L Number	Hits	Search Text	DB	Time stamp
1	2	(rotation\$3 with position with shaft) and (ripple with signal) and (slope with detect\$ with signal) and magnitude	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:16
2	1	(slope with detect\$3 with signal) and motor and (rotation\$3 with position) and (ripple with signal) and (sampl\$3 with armature with signal)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:16
3	1	((rotation\$3 with position with shaft) and (ripple with signal) and (slope with detect\$ with signal) and magnitude) and ((ris\$3 or fall\$3) with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:17
4	1	((rotation\$3 with position with shaft) and (ripple with signal) and (slope with detect\$ with signal) and magnitude) and ((increas\$3 or decreas\$3) with tendency)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:18
5	0	((rotation\$3 with position with shaft) and (ripple with signal) and (slope with detect\$ with signal) and magnitude) and (identif\$4 with tendency)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:18
6	0	((rotation\$3 with position with shaft) and (ripple with signal) and (slope with detect\$ with signal) and magnitude) and (identif\$8 with tendency)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:18
	4	("6144179" "4881174").pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:14
	10	DE-3721827-\$ did. or DE-4017779-\$ did. or DE-4217265-\$ did. or DE-19834108-\$ did. or DE-19511307-\$ did. or DE-19729238-\$ did.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:07
	0	((DE-3721827-\$ did. or DE-4017779-\$ did. or DE-4217265-\$ did. or DE-19834108-\$ did. or DE-19511307-\$ did. or DE-19729238-\$ did.) or ("6144179" "4881174").pn.) and (time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:10
	1	(time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:12
	8	(time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:23
	1	((time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:12

	1	(armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:18
	1	(armature with signal) and (ripple with slope with detect\$3 with signal)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:15
	0	("6144179" "4881174").pn.) and slope	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:14
	3	((armature with signal) and (ripple with slope) and (ripple with signal)) and (slope with detect\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:15
	1	((armature with signal) and (ripple with slope) and (ripple with signal)) and (slope with detect\$3)) and (ris\$3 with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:18
	3	((armature with signal) and (ripple with slope) and (ripple with signal)) and (slope with detect\$3)) and (sampl\$3 with point)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:19
	1	((((armature with signal) and (ripple with slope) and (ripple with signal)) and (slope with detect\$3)) and (sampl\$3 with point)) and (compar\$6 same (sampl\$3 with point) same (sampl\$3 with armature))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:20
	5	(armature with signal) and (ripple with slope) and (ripple with signal)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:20
	8	((time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)) and motor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:51
	1	(((time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)) and motor) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 13:24
	3	(ris\$3 with ripple with slope) and (fall\$3 with ripple with slope) and (slope with detect\$3)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:17
	1	((ris\$3 with ripple with slope) and (fall\$3 with ripple with slope) and (slope with detect\$3)) and (compar\$3 same (armature with signal))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:22

	3	((ris\$3 with ripple with slope) and (fall\$3 with ripple with slope) and (slope with detect\$3)) and (compar\$3 same (time with point))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:27
	1	((((ris\$3 with ripple with slope) and (fall\$3 with ripple with slope) and (slope with detect\$3)) and (compar\$3 same (time with point))) and ((increas\$3 or decreas\$3) with tendency with magnitude)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:25
	1	((((ris\$3 with ripple with slope) and (fall\$3 with ripple with slope) and (slope with detect\$3)) and (compar\$3 same (time with point))) and ((increas\$3 or decreas\$3) with tendency))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:26
	1	((time with point) and (armature with signal) and (stor\$3 with armature) and (compar\$3 with armature) and (slope with detect\$3)) and motor and (rotation\$3 with position)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:52
	1	702/.ccls. and (slope with detect\$3) and motor and (rotation\$3 with position) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 15:53
	4	(slope with detect\$3) and motor and (rotation\$3 with position) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 17:14
	1	(slope with detect\$3) and motor and (rotation\$3 with position with shaft) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 16:12
	3	motor and (rotation\$3 with position with shaft) and (ripple with slope)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 16:14
	411	motor and (rotation\$3 with position with shaft) and ripple ((slope with detect\$) same mangnitude)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 16:21
	0	motor and (rotation\$3 with position with shaft) and ripple and ((slope with detect\$) same mangnitude)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 16:21
	2	motor and (rotation\$3 with position with shaft) and ripple and ((slope with detect\$) same magnitude)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/09/25 16:53